



# Reinforcement Learning for Spacecraft in Stochastic Environments

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# Stochastic Environments

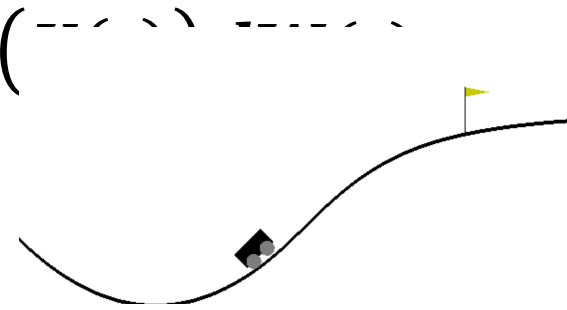
- Stochastic Differential Equations (SDE)

$$dX = f(X(t))dt + g(\dots)$$

- Mountain Car

$$d\vec{r} = \vec{v}$$

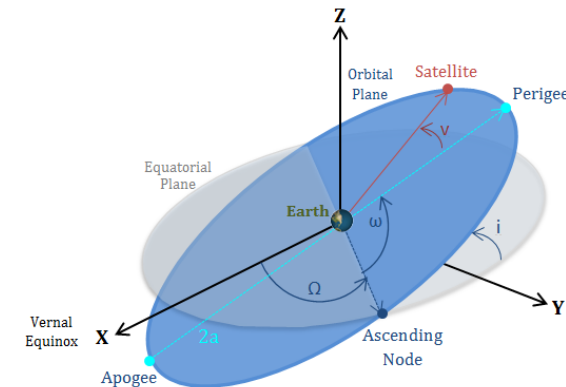
$$d\vec{v} = \overrightarrow{a_{grav}} + \frac{\vec{u}}{m} + \sigma dW(t)$$



- Orbits

$$d\vec{r} = \vec{v}$$

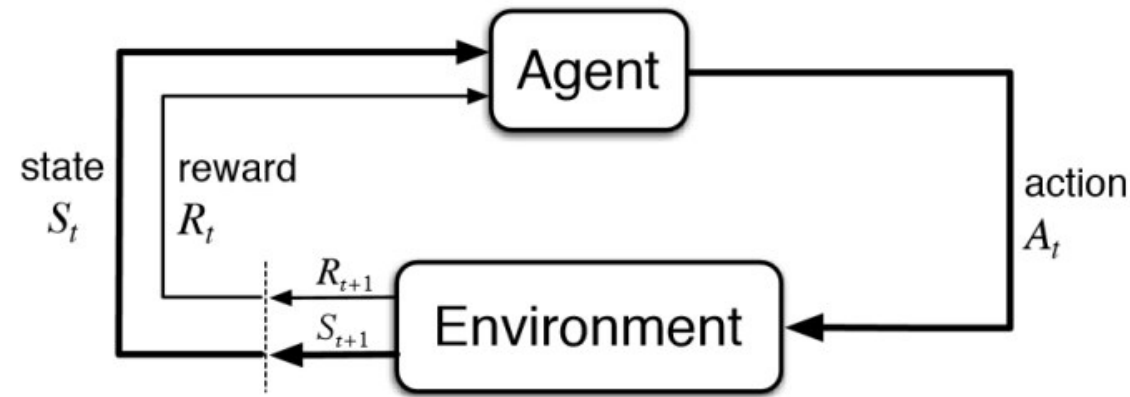
$$d\vec{v} = \frac{\mu}{r^3} \hat{r} + \overrightarrow{a_{pert}} + \frac{\vec{u}}{m} + \sigma dW(t)$$





# Reinforcement Learning

- Agent Seeks to Accumulate Reward



- Bellman Function

$$V^\pi = R(s, \pi(s)) + \gamma \sum_{s'} P(s'|s, a) V^{\pi^*}(s')$$



# Conclusions & Future Work

- Noisy Environments
  - Stochastic Value Gradient (Heess et al., 2015)
- Sparse Rewards
  - Potential-Based Reward Shaping
  - $F(s, a, s') = \gamma\phi(s') - \phi(s)$
- Reward Design in Orbital Environment
  - Keplerian vs. Cartesian
- Future Work
  - More Realistic & Complex Orbit Environment
  - Augmented Experience Replay
  - Incorporating Approximations of Fokker-Planck



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