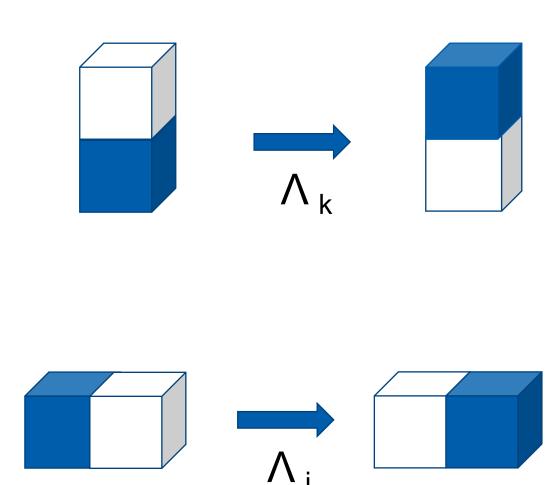


Machine Learning Application to Sand Dune Model Prediction Using Generative Adversarial Networks (GAN's)

ReSCAL (real-space cellular automaton laboratory) is a simulation software used to make geomorphic predictions of sand dunes using a simple cellular automata structure. These simulations require a vast amount of both computing time and memory. Here we train a GAN to make video predictions of the sand dune model at a certain time step, F_{T} .

SAND DUNE PREDICTIONS ARE COMPUTATIONALLY EXPENSIVE

Each cell is treated as a "doublet", or a nearest neighbor cell, within the cell space



Source: http://rescal.geophysx.org/

- A 50 x 200 x 80 3D space takes 20 minutes to generate the predicted model at T_{500}^{1}
- A 100 x 1800 x 200 3D space requires around 24 hours to generate the predicted model at T_{500}

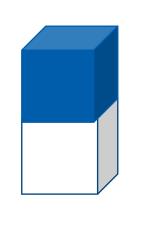
 ${}^{1}T_{500}$ is equivalent to the state of the model 13 days into the future.

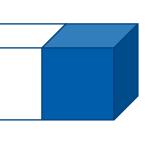
This work performed under the auspices of the U.S. Department of Energy by Lawrence Livermore National Laboratory under Contract DE-AC52-07NA27344.

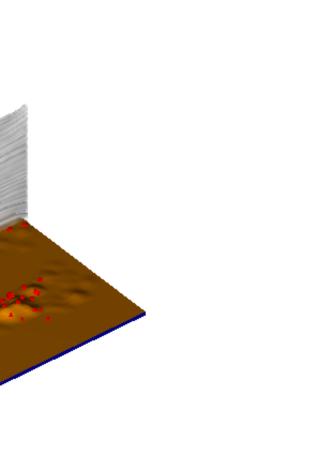


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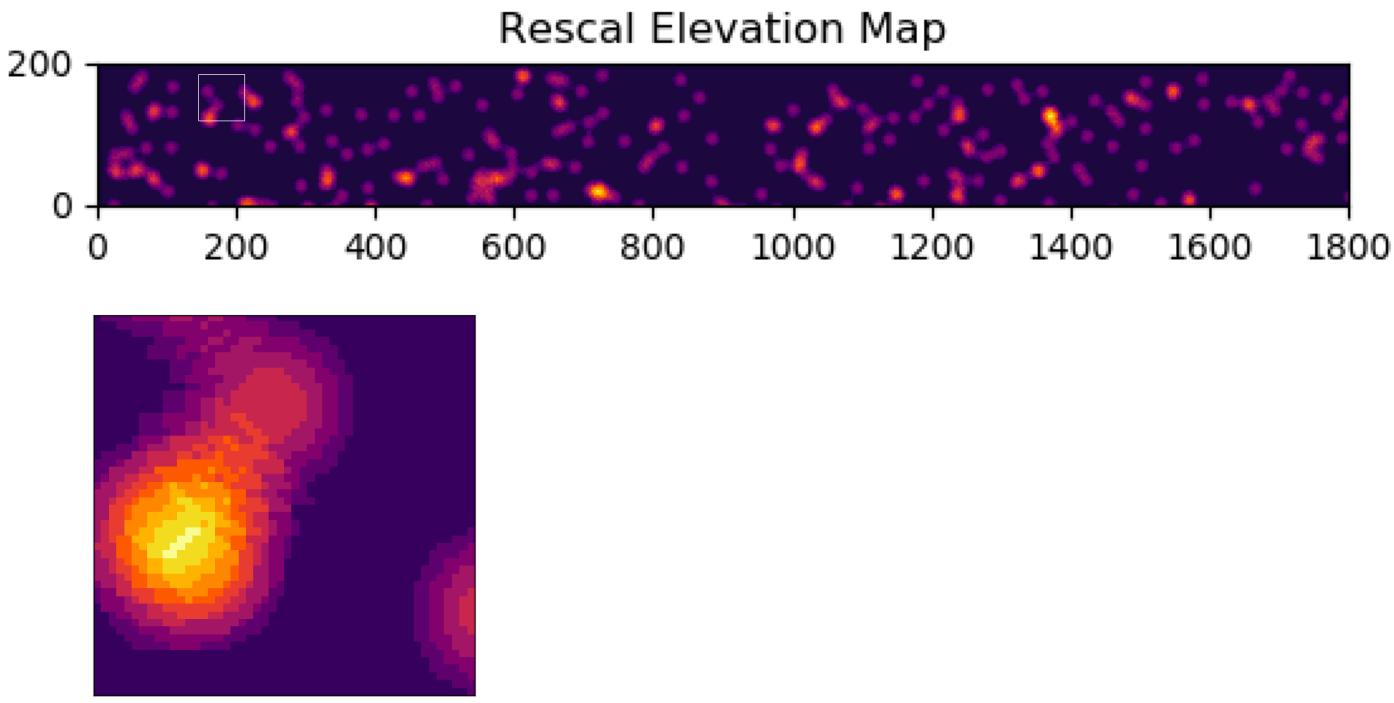






SIMULATING SAND DUNE DATA

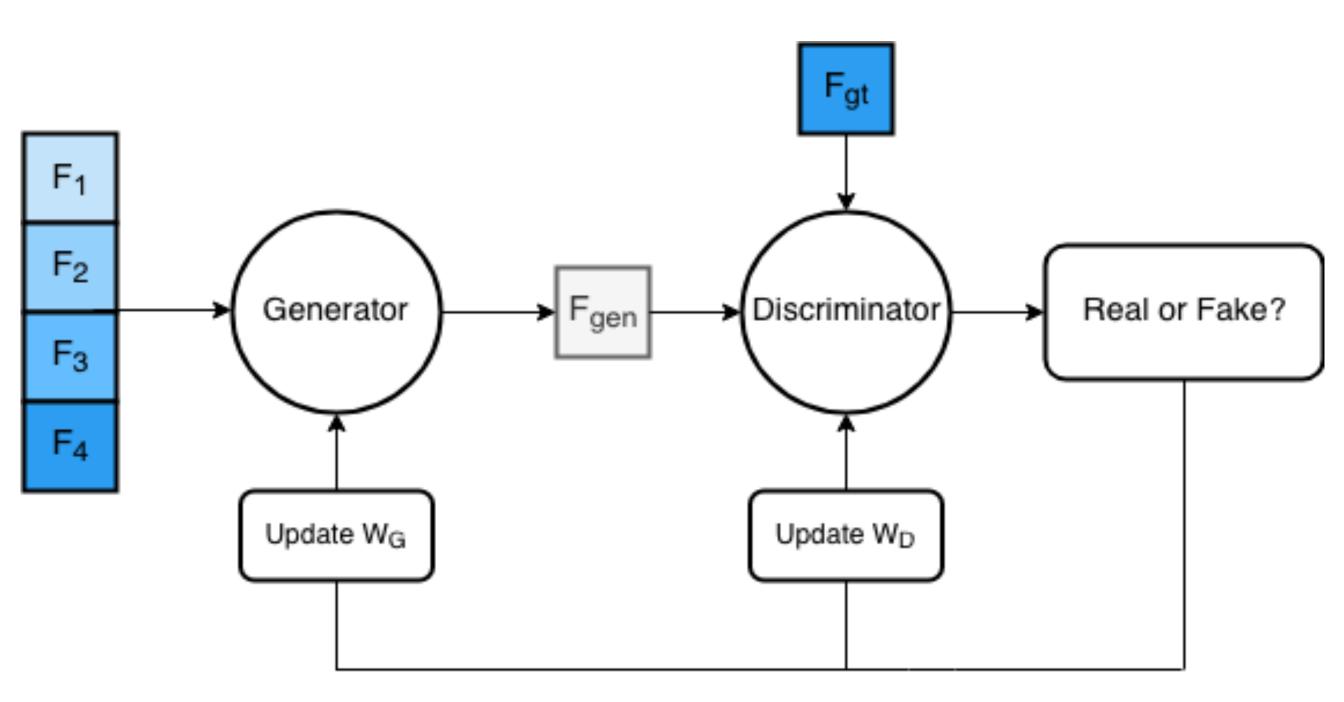
- Generate sand dune elevation values for a 3D model with dimensions 100 x 1800 x 200 until T_{500}
- Split each frame into 32 x 32 crops for training • Train the GAN model to generate predictions of the next frame
- given the first four frames of the model



VIDEO PREDICTION USING A GAN

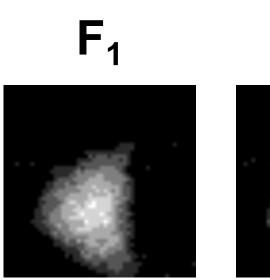
Generative Adversarial Networks

- Generator learns to create accurate predictions of the next frame given the past four frames
- Discriminator, or the "adversary", learns to differentiate between "real" and "fake" frames
- The generator makes more accurate predictions of the next frame, attempting to "fool" the discriminator

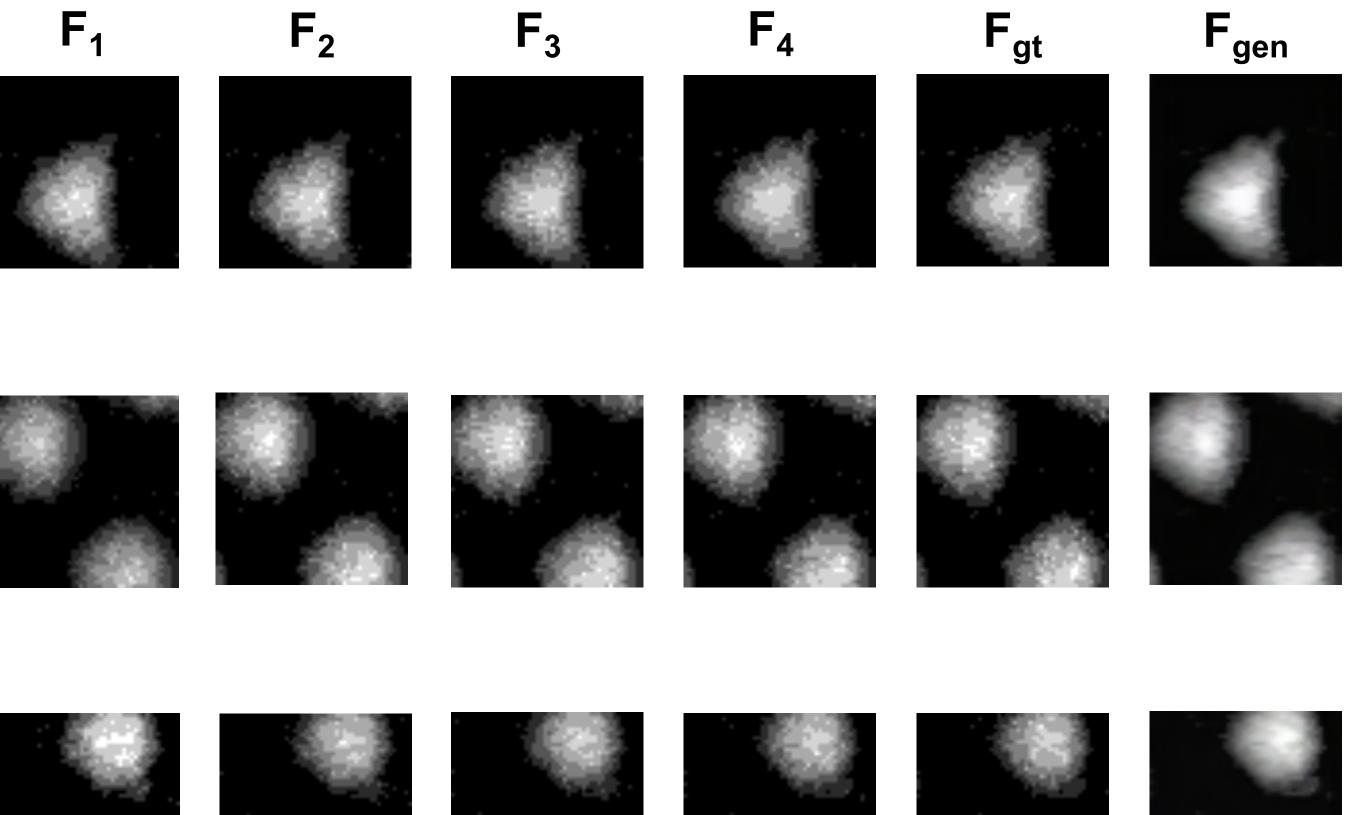


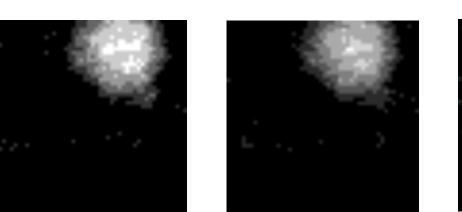
Objective: Train a GAN to make accurate predictions of the sand dune model at F_5 .

PREDICTED FRAME F₅









DISCUSSION/FUTURE WORK

- the predictions will never be 100% accurate
- adversarial network

REFERENCES

- Mathieu, Michael, Camille Couprie, and Yann LeCun. "Deep multi-scale video prediction beyond mean square error." arXiv preprint arXiv:1511.05440 (2015).
- Rozier, Olivier, and Clément Narteau. "A real-space cellular automaton laboratory." Earth Surface Processes and Landforms 39.1 (2014): 98-109.
- https://github.com/dyelax/Adversarial_Video_Generation.

• High level of abstraction when we treat this as a video prediction problem – we only train the model on the output at each time step • Due to the inherent stochastic behavior of these sand dune models,

• Compare the results for training the adversarial network and the non-

• Train the model using images that contain a longer period of time in between each one in order to capture and predict more movement

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